1. ROS python3 설정

<https://medium.com/@beta_b0t/how-to-setup-ros-with-python-3-44a69ca36674>

1. python3 get-pip.py

<https://pip.pypa.io/en/stable/installation/>

1. sudo apt install python3-testresources
2. pip3 install --upgrade pip setuptools wheel
3. pip3 install --no-binary opencv-python opencv-python

(굉장히 오래걸림)

1. pip3 install qimage2ndarray
2. pip3 install pyqt5